

Unit:- 2 \div Scalar And Vector

Scalar Quantities:-

* The physical quantity having only magnitude are called scalar quantities.

Ex:- Mass, length, volume, density, Energy, temperature, Electric charge etc.

Vector Quantities:-

* The physical quantities having both magnitude as well as direction are called vector quantities.

Ex:- Displacement, velocity, acceleration, force, electric intensity, magnetic intensity, magnetic moment etc.

Representation of a vector:-

* A vector is written with an arrow head over its symbol like \vec{x} .

* Examples:- Acceleration (\vec{a}).

velocity (\vec{v}).

force (\vec{F}).

Types of vector:-

1) Null Vector:-

The vector having 0 magnitude and an arbitrary ~~constant~~ direction is called a null vector.

2) Equal vector:-

Two vectors are said to be equal if they possess the same magnitude and direction.

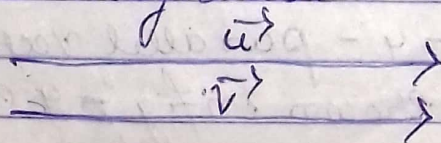


Fig:- 1:- Equal vectors

(ii) Negative Vectors:-

A vector is said to be a ~~major~~ negative vector of another one if it is represented by a line having same length as that of the second and is directed in opposite direction.

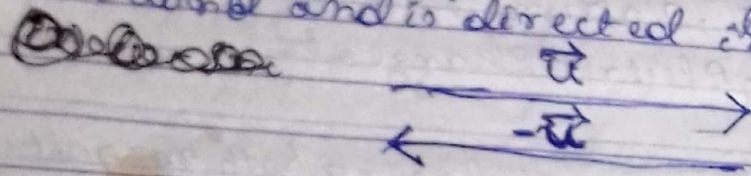


Fig:- 2:- Negative Vector

(iv) Co-Initial Vector:-

* A number of vectors having a common initial point are called co-initial vectors.

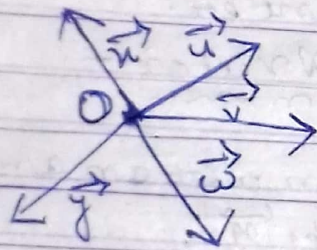


Fig:- 3:- Co-Initial Vectors

(v) Collinear Vector:- * Vectors having a common line of action are called collinear vector.

* There are two types of collinear vectors.

a) parallel vector:- ($\theta = 0^\circ$)

→ Two vectors (which may have different magnitudes) acting along same direction are parallel vectors.

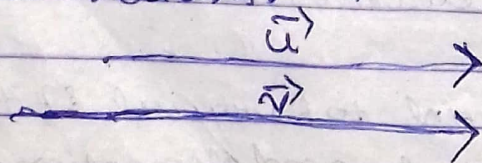


Fig:- 4:- parallel vectors

* Vectors \vec{u} and \vec{v} shown in fig:- 4 are parallel and angle betⁿ them is 0° .

(g) Anti parallel Vector:-

* Two vectors which are directed in opposite directions are called Anti-parallel vectors.

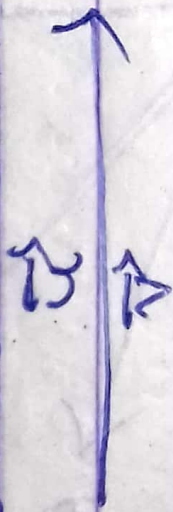


Fig.:- Anti-parallel vectors.

* Vectors \vec{u} and \vec{v} shown in Figure 5 are antiparallel vector and angle between them is 180° .

(vi) Co-planar vector:-

* Vectors situated in one plane irrespective of their directions are known as co-planar vectors.

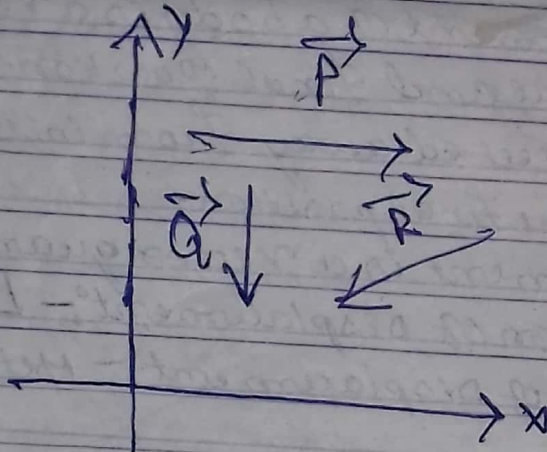


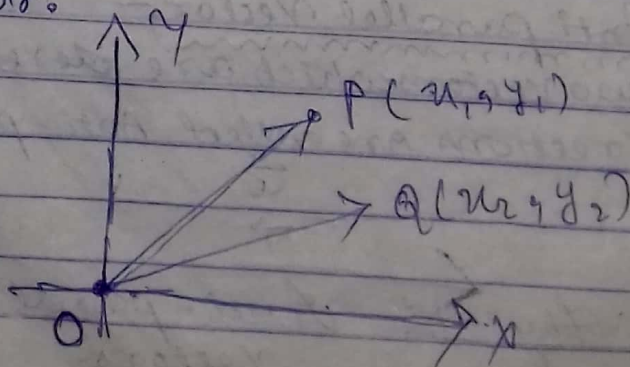
Fig:- Co-planar vector

* Vectors \vec{p} , \vec{q} and \vec{r} drawn in xy plane are co-planar vectors.

(vii) Localised vector:-

* Vector whose initial point (tail) is fixed is said to be a localised or a fixed vector.

* position vector of every point starts from origin, so it can be considered as a localised or fixed vector.



(iii) Non-Localised vector:-

- * Vector whose initial point (tail) is not fixed is said to be a non-localised vector or a free vector.
- * Vectors representing force, momentum etc. are Non-Localised vectors.

Triangle Law of vector Addition:-

- * It is a law for the addition of two vectors. It can be stated as follows:- "If two vectors are represented (in magnitude and direction) by the two sides of a triangle taken in same order then their resultant is represented (in magnitude and direction) by the third side of the triangle taken in opposite order."

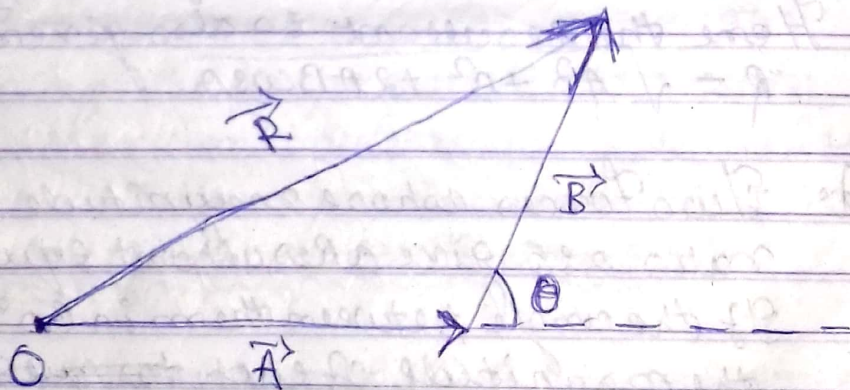


Fig:- 7:- Vector Addition By Triangle Law

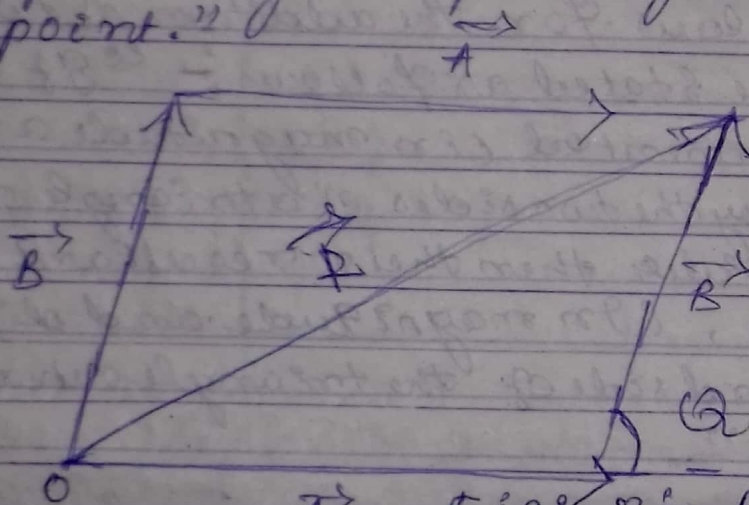
- * Resultant of two vectors \vec{A} and \vec{B} acting at a point can be determined by triangle law. The resultant is given by,

$$R = \sqrt{A^2 + B^2 + 2AB \cos \theta} \quad \text{--- (i)}$$

where, θ is the angle between \vec{A} and \vec{B} .

Parallelogram Law of Vector Addition:-

It states that if two vectors acting simultaneously at a point represented (in magnitude and direction) by the two sides of parallelogram drawn from a point then their resultant is given (in magnitude or direction) by the diagonal of the parallelogram passing through that point."



Here the resultant is also given by
 $R = \sqrt{A^2 + B^2 + 2AB \cos \theta}$

Q. Two forces whose magnitude are in the ratio 3:5 give a resultant equal to 70N. If the angle between them is 60° . Find the magnitude of each force.

Ans:- Given that $\frac{F_1}{F_2} = \frac{3}{5}$; $R = 70\text{N}$; $\theta = 60^\circ$

We know that $R = \sqrt{F_1^2 + F_2^2 + 2F_1F_2 \cos \theta}$

$$\Rightarrow R^2 = F_1^2 + F_2^2 + 2F_1F_2 \cos \theta$$

$$\Rightarrow (70)^2 = \left(\frac{3}{5}F_2\right)^2 + F_2^2 + 2 \times \frac{3}{5}F_2 \times F_2 \times \cos 60^\circ$$

$$\Rightarrow 4900 = \frac{9}{25}F_2^2 + F_2^2 + \frac{6}{5}F_2^2 \times \frac{1}{2}$$

$$\Rightarrow 4900 = \frac{9}{25} F_2^2 + F_2^2 + \frac{3}{5} F_2^2$$

$$\Rightarrow 4900 = F_2^2 \left(\frac{9}{25} + \frac{3}{5} + 1 \right)$$

$$\Rightarrow 4900 = F_2^2 \left(\frac{9}{25} + \frac{3}{5} + 1 \right)$$

$$\Rightarrow 4900 = F_2^2 \left(\frac{9 + 15 + 25}{25} \right)$$

$$\Rightarrow 4900 = F_2^2 \left(\frac{49}{25} \right)$$

$$\Rightarrow F_2^2 = 4900 \times \frac{25}{49} = 2500$$

$$\Rightarrow F_2 = \sqrt{2500} = 50 \text{ N}$$

$$\therefore F_1 = \frac{3}{5} F_2 = \frac{3}{5} \times 50 = 30 \text{ N}$$

Resolution of vectors in a plane:-

Resolution of vectors is the process of obtaining the component of the vector which when combined according to the laws of vector addition produced the given vector.

Rectangular components of a vector:-

Rectangular components of a given vector, are its components in two mutually perpendicular directions in the plane of the given vector.

Let \vec{OP} (\vec{R}) be the position vector of a point $P(x, y)$.

Applying Law of $\triangle OAP$.

$$\vec{OP} = \vec{OA} + \vec{AP}$$

$$\Rightarrow \vec{r} = \vec{OA} + \vec{OB}$$

$$= x\hat{i} + y\hat{j}$$

In ΔOAP ,

$$\cos\theta = \frac{b}{h} = \frac{OA}{OP} = \frac{x}{R}$$

$$x = R \cos\theta$$

In OAP triangle,

$$\sin\theta = \frac{p}{h} = \frac{AP}{OP} = \frac{OB}{OP}$$

$$= \frac{y}{R}$$

$$\Rightarrow y = R \sin\theta$$

$$\therefore \vec{r} = R \cos\theta \hat{i} + R \sin\theta \hat{j}$$

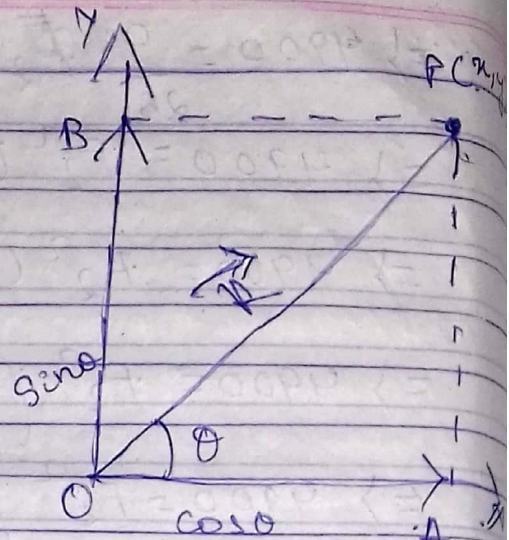


Fig: 9: Rectangular components of a vector.

Product of Two Vectors:-

There are two ways in which two vectors can be multiplied together.

- (i) Dot product or Scalar product.
- (ii) Cross product or Vector product.

(i) Dot product or Scalar product:-

Dot product of two vectors is defined as the product of their magnitudes and the cosine of the smaller angle between the two.

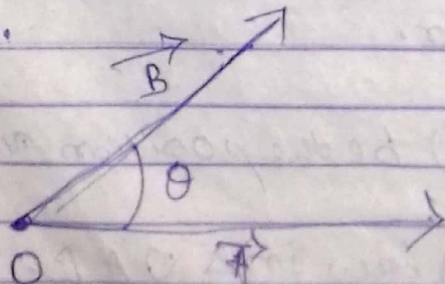


Fig: 10

Dot product of \vec{A} and \vec{B} is given by $\vec{A} \cdot \vec{B} = AB \cos \theta$ — (i) where θ is the angle betⁿ \vec{A} & \vec{B} .

Characteristics of Dot product :-

(i) Commutative :- $\vec{A} \cdot \vec{B} = \vec{B} \cdot \vec{A}$

(ii) Distributive :- $\vec{A} \cdot (\vec{B} + \vec{C} + \vec{D}) = \vec{A} \cdot \vec{B} + \vec{A} \cdot \vec{C} + \vec{A} \cdot \vec{D}$

(iii) perpendicular vector :- The dot product of two perpendicular vectors is always zero.

Ex :- For perpendicular vectors \vec{A} and \vec{B}

$$\theta = 90^\circ$$

$$\vec{A} \cdot \vec{B} = AB \cos \theta = AB \cos (90^\circ) = AB \times 0 = 0.$$

(iv) Dot product in terms of Rectangular components :-

$$\hat{i} \cdot \hat{j} = 0 = \hat{j} \cdot \hat{i} \quad \hat{i} \cdot \hat{i} = \hat{j} \cdot \hat{j} = \hat{k} \cdot \hat{k} = 1$$

$$\hat{j} \cdot \hat{k} = 0 = \hat{k} \cdot \hat{j}$$

$$\hat{k} \cdot \hat{i} = 0 = \hat{i} \cdot \hat{k}$$

Let A_x, A_y, A_z and B_x, B_y, B_z be the Rectangular Components of vectors \vec{A} & \vec{B}

$$\vec{A} = A_x \hat{i} + A_y \hat{j} + A_z \hat{k}$$

$$\vec{B} = B_x \hat{i} + B_y \hat{j} + B_z \hat{k}$$

$$\begin{aligned} \vec{A} \cdot \vec{B} &= (A_x \hat{i} + A_y \hat{j} + A_z \hat{k}) \cdot (B_x \hat{i} + B_y \hat{j} + B_z \hat{k}) \\ &= A_x \hat{i} (B_x \hat{i} + B_y \hat{j} + B_z \hat{k}) + A_y \hat{j} (B_x \hat{i} + B_y \hat{j} + B_z \hat{k}) \\ &\quad + A_z \hat{k} (B_x \hat{i} + B_y \hat{j} + B_z \hat{k}) \end{aligned}$$

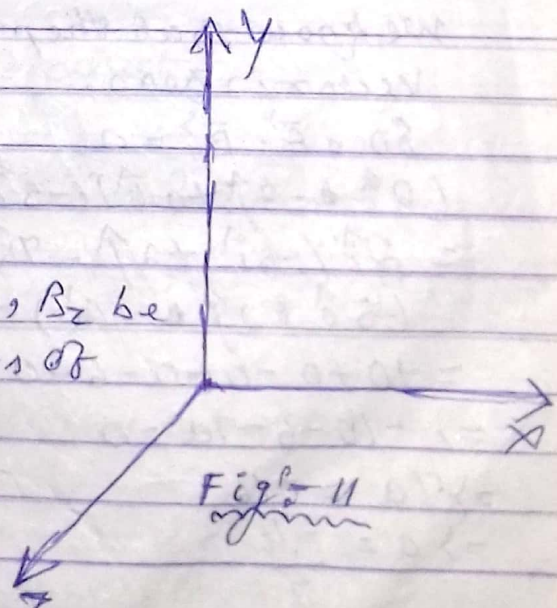


Fig-11

$$\begin{aligned}
 &= (A_1 \hat{i} \cdot B_1 \hat{i}) + (A_1 \hat{i} \cdot B_2 \hat{j}) + (A_1 \hat{i} \cdot B_3 \hat{k}) + (A_2 \hat{j} \cdot B_1 \hat{i}) + (A_2 \hat{j} \cdot B_2 \hat{j}) + (A_2 \hat{j} \cdot B_3 \hat{k}) + (A_3 \hat{k} \cdot B_1 \hat{i}) + (A_3 \hat{k} \cdot B_2 \hat{j}) + (A_3 \hat{k} \cdot B_3 \hat{k}) \\
 &= A_1 B_1 + 0 + 0 + 0 + A_2 B_2 + 0 + 0 + 0 + A_3 B_3 \\
 &= A_1 B_1 + A_2 B_2 + A_3 B_3
 \end{aligned}$$

Q. Given that $\vec{A} = \hat{i} - 2\hat{j} - 3\hat{k}$,
 $\vec{B} = 2\hat{i} + \hat{j} - 5\hat{k}$.

Find $\vec{A} \cdot \vec{B}$

$$\begin{aligned}
 &= (\hat{i} - 2\hat{j} - 3\hat{k}) \cdot (2\hat{i} + \hat{j} - 5\hat{k}) \\
 &= \hat{i}(2\hat{i} + \hat{j} - 5\hat{k}) - 2\hat{j}(2\hat{i} + \hat{j} - 5\hat{k}) - 3\hat{k}(2\hat{i} + \hat{j} - 5\hat{k})
 \end{aligned}$$

$$= 2 + 0 - 0 - 0 - 2 + 0 - 0 - 0 + 15$$

$$= 2 - 2 + 15 = 15$$

Q. Given that $\vec{A} = (2\hat{i} - 3\hat{j} + a\hat{k})$
 $\vec{B} = (-5\hat{i} + 2\hat{j} - 7\hat{k})$

Find the value of a if \vec{A} and \vec{B} are perpendicular to each other.

We know that the product of two perpendicular vectors is zero.

$$\text{So } \vec{A} \cdot \vec{B} = 0.$$

$$(2\hat{i} - 3\hat{j} + a\hat{k}) \cdot (-5\hat{i} + 2\hat{j} - 7\hat{k}) = 0$$

$$= 2\hat{i}(-5\hat{i} + 2\hat{j} - 7\hat{k}) - 3\hat{j}(-5\hat{i} + 2\hat{j} - 7\hat{k}) + a\hat{k}(-5\hat{i} + 2\hat{j} - 7\hat{k}) = 0.$$

$$= -10 + 0 - 0 - 0 - 6 - 0 + 0 + 0 - 7a = 0$$

$$\Rightarrow -10 - 6 - 7a = 0$$

$$\Rightarrow 7a = -16$$

$$\Rightarrow a = \frac{-16}{7}$$

Cross product or Vector product:-

Cross product of two vectors \vec{A} and \vec{B} is defined as a single vector \vec{C} whose magnitude is equal to the product of their individual magnitude and the sign of the smaller angle between them and is directed along the Normal to the plane containing \vec{A} & \vec{B} .

$$\vec{A} \times \vec{B} = AB \sin \theta \cdot \hat{n} \quad \text{--- (i)}$$

Where \hat{n} is the unit vector in a direction perpendicular to the plane containing \vec{A} & \vec{B} .

The direction of cross product can be determined by the application of following Rule.

Right Hand Thumb Rule:-

If the fingers curl in the direction from \vec{A} to \vec{B} then the direction of thumb gives the direction of $\vec{A} \times \vec{B}$.

Characteristics of cross product:-

(i) Non-Commutative :- $\vec{A} \times \vec{B} \neq \vec{B} \times \vec{A}$

$$\vec{A} \times \vec{B} = -(\vec{B} \times \vec{A})$$

(ii) Distributive :- $\vec{A} \times (\vec{B} + \vec{C} + \vec{D}) = \vec{A} \times \vec{B} + \vec{A} \times \vec{C} + \vec{A} \times \vec{D}$.

(iii) Parallel Vectors :- Cross product of two parallel vectors is always zero.

Ex:- For parallel vectors \vec{A} and \vec{B} , $\theta = 0^\circ$

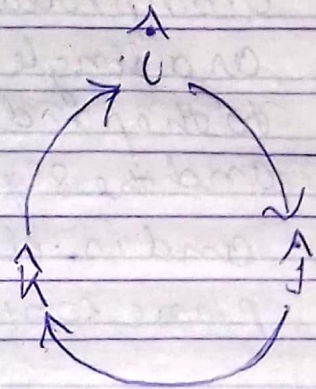
$$\vec{A} \times \vec{B} = AB (\sin 0^\circ) \hat{n} = 0.$$

* In case of perpendicular & orthogonal unit vectors.

$$\begin{aligned} \hat{i} \times \hat{j} &= \hat{k} \\ \hat{j} \times \hat{k} &= \hat{i} \\ \hat{k} \times \hat{i} &= \hat{j} \end{aligned}$$

$$\begin{aligned} \hat{j} \times \hat{i} &= -\hat{k} \\ \hat{k} \times \hat{j} &= -\hat{i} \\ \hat{i} \times \hat{k} &= -\hat{j} \end{aligned}$$

$$\begin{aligned} \hat{i} \times \hat{i} &= 0 \\ \hat{j} \times \hat{j} &= 0 \\ \hat{k} \times \hat{k} &= 0 \end{aligned}$$



(iv) Cross product in terms of Rectangular Component :-

Fig: $\vec{i}, \vec{j}, \vec{k}$ cyclic

Let A_x, A_y, A_z and B_x, B_y, B_z be the Rectangular component of \vec{A} & \vec{B} , then,

$$\begin{aligned} \vec{A} &= A_x \hat{i} + A_y \hat{j} + A_z \hat{k} \\ \vec{B} &= B_x \hat{i} + B_y \hat{j} + B_z \hat{k} \end{aligned}$$

$$\therefore \vec{A} \times \vec{B} = (A_x \hat{i} + A_y \hat{j} + A_z \hat{k}) (B_x \hat{i} + B_y \hat{j} + B_z \hat{k})$$

$$= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix}$$

$$= \hat{i} \begin{vmatrix} A_y & A_z \\ B_y & B_z \end{vmatrix} - \hat{j} \begin{vmatrix} A_x & A_z \\ B_x & B_z \end{vmatrix} + \hat{k} \begin{vmatrix} A_x & A_y \\ B_x & B_y \end{vmatrix}$$

$$= \hat{i} (A_y B_z - A_z B_y) - \hat{j} (A_x B_z - A_z B_x) +$$

$$\hat{k} (A_x B_y - A_y B_x)$$

Problem: 4 :- $\vec{A} = 2\hat{i} + 3\hat{j} + 4\hat{k}$
 $\vec{B} = \hat{i} + 2\hat{j} + 3\hat{k}$

Find $\vec{A} \times \vec{B} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 2 & 3 & 4 \\ 1 & 2 & 3 \end{vmatrix}$

$$\Rightarrow \det(A - \lambda I) = \det \begin{pmatrix} 9 - \lambda & -1 \\ -2 & 5 - \lambda \end{pmatrix} + k \det \begin{pmatrix} -2 & -1 \\ -1 & 3 \end{pmatrix}$$

$$\Rightarrow 17\lambda - 2k = 0$$

$$\Rightarrow \lambda = \frac{2k}{17}$$